

大大特: 動力学パラメータの研究 動力学モデルの強震動への応用

⌘ 動力学モデルの導入法

(2通りの方法)

- ☒ 震源過程・強震動同時シミュレーション
- ☒ 動力学モデルの近似式

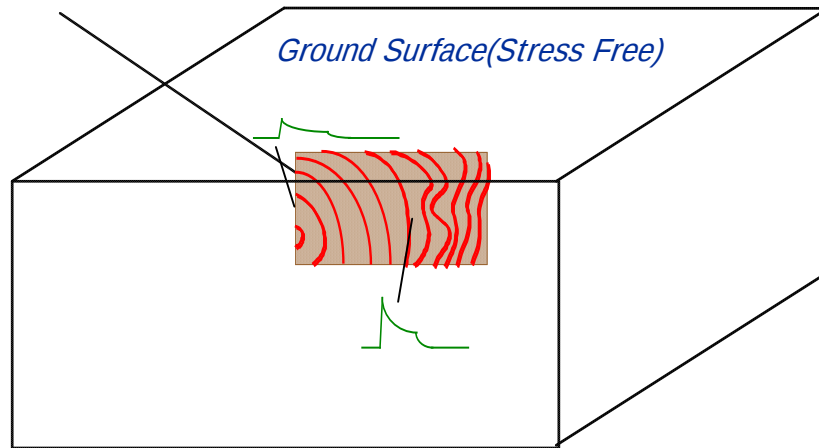
Dynamic modeling

Stress release process whether rupture is spontaneous or not.

Dynamic problem in Local area

Fault constitutive law

$$\tau = f\left(\Delta u, \frac{\partial \Delta u}{\partial t}, \theta, T, \dots\right) \quad \text{If } \tau > \tau_p \text{ or } t > T_r(x, z)$$



Absorbing Boundary Condition

$$\rho \frac{\partial v_1}{\partial t} = \frac{\partial \tau_{11}}{\partial x_1} + \frac{\partial \tau_{12}}{\partial x_2} + \frac{\partial \tau_{13}}{\partial x_3}$$

$$\rho \frac{\partial v_2}{\partial t} = \frac{\partial \tau_{21}}{\partial x_1} + \frac{\partial \tau_{22}}{\partial x_2} + \frac{\partial \tau_{23}}{\partial x_3}$$

$$\rho \frac{\partial v_3}{\partial t} = \frac{\partial \tau_{31}}{\partial x_1} + \frac{\partial \tau_{32}}{\partial x_2} + \frac{\partial \tau_{33}}{\partial x_3}$$

$$\frac{\partial \tau_{11}}{\partial t} = (\lambda + 2\mu) \frac{\partial v_1}{\partial x_1} + \lambda \frac{\partial v_2}{\partial x_2} + \lambda \frac{\partial v_3}{\partial x_3}$$

$$\frac{\partial \tau_{22}}{\partial t} = \lambda \frac{\partial v_1}{\partial x_1} + (\lambda + 2\mu) \frac{\partial v_2}{\partial x_2} + \lambda \frac{\partial v_3}{\partial x_3}$$

$$\frac{\partial \tau_{33}}{\partial t} = \lambda \frac{\partial v_1}{\partial x_1} + \lambda \frac{\partial v_2}{\partial x_2} + (\lambda + 2\mu) \frac{\partial v_3}{\partial x_3}$$

$$\frac{\partial \tau_{12}}{\partial t} = \mu \left(\frac{\partial v_1}{\partial x_2} + \frac{\partial v_2}{\partial x_1} \right)$$

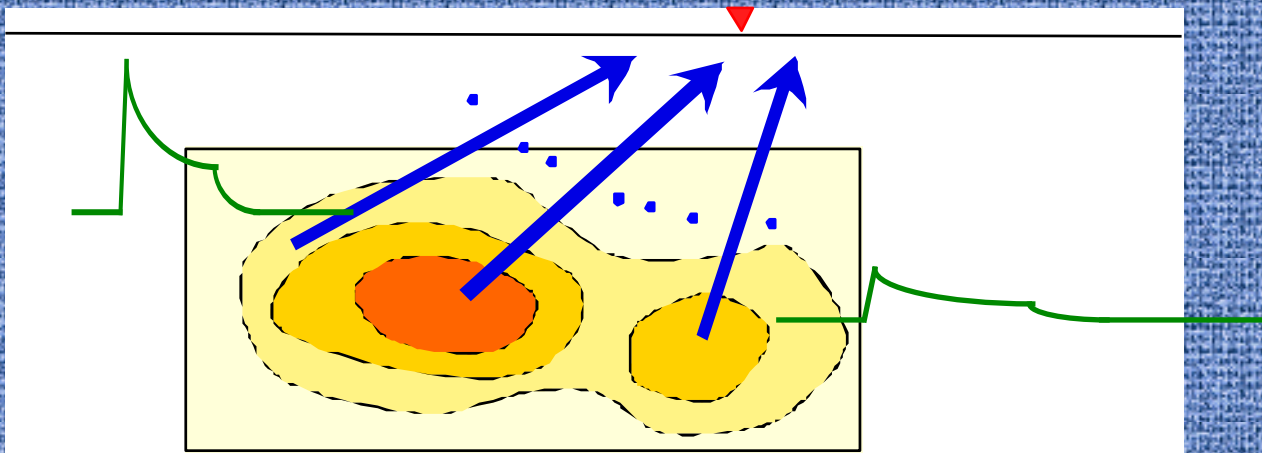
$$\frac{\partial \tau_{13}}{\partial t} = \mu \left(\frac{\partial v_1}{\partial x_3} + \frac{\partial v_3}{\partial x_1} \right)$$

$$\frac{\partial \tau_{23}}{\partial t} = \mu \left(\frac{\partial v_2}{\partial x_3} + \frac{\partial v_3}{\partial x_2} \right)$$

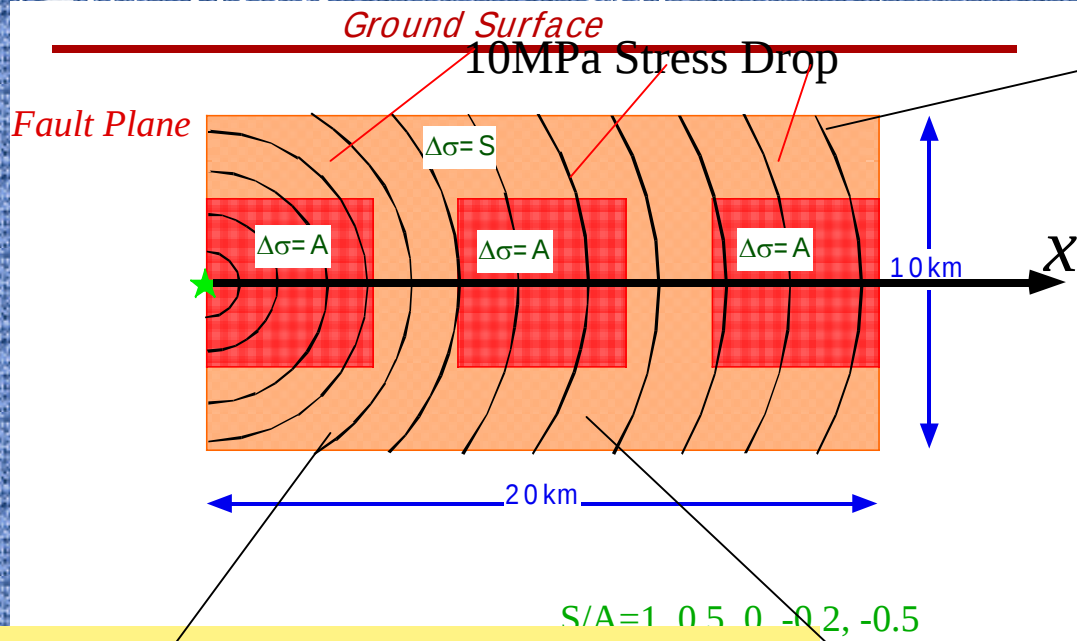
すべり速度時間関数の近似式

⌘ 2 approaches

- ☒ FD (or FEM) Simulation of Dynamic Faulting process
- ☒ Seismic wave from slip time history based on dynamic source model
 - ☒ Approximate expression of slip rate time function for dynamic rupture

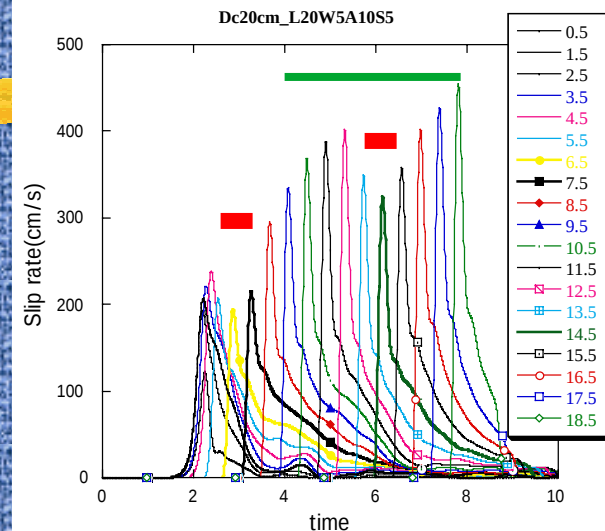


近似式作成のための数値シミュレーション



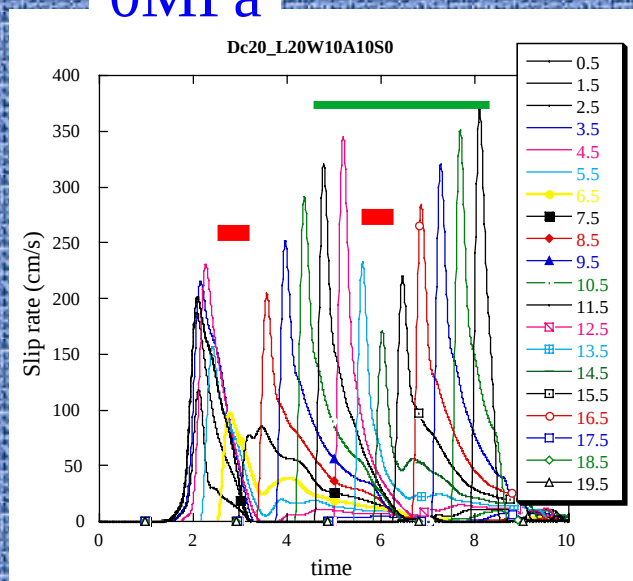
+5MPa

$S/A = 0.5$

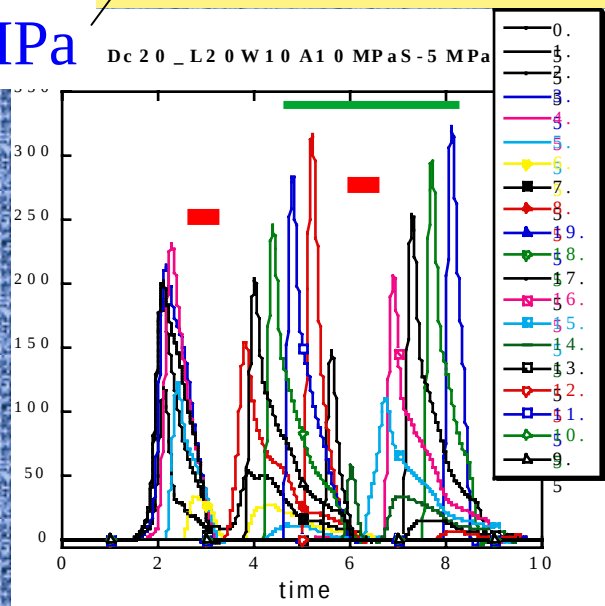


Slip rate time history along x-axis

0MPa

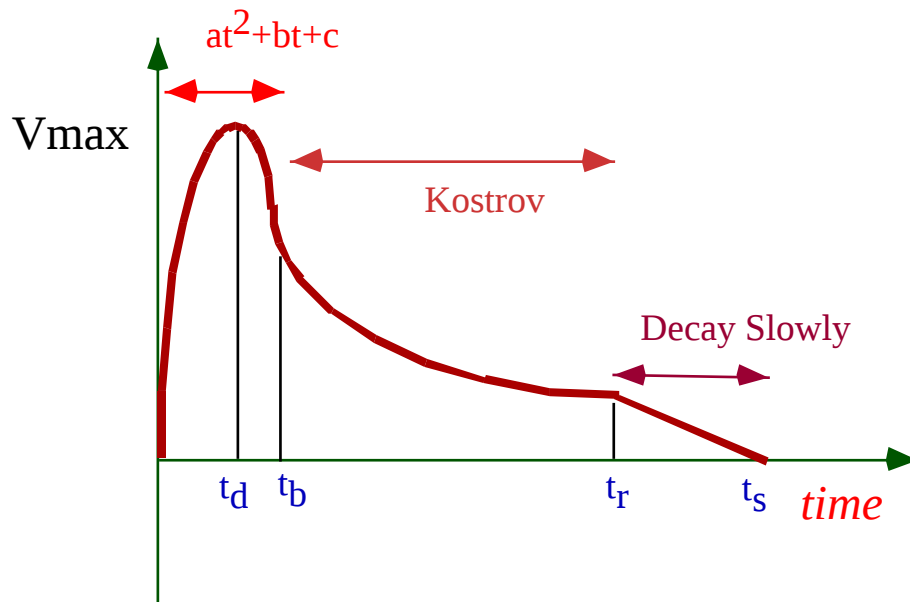


-5MPa



近似式

Slip Velocity



パラメータ

V_m, t_d, t_b, t_r, t_s

必要な情報

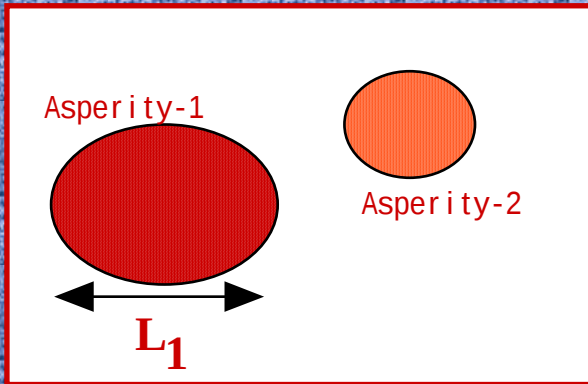
V_m (又は $\Delta\sigma$)

t_d (又は $f_{\max}$)

すべり量

ライズタイム

パラメータの決め方



Asperity

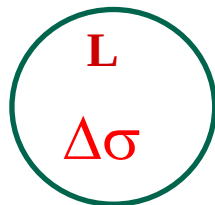
Location

Size

Stress Drop

L

$\Delta\sigma$



Rise time $t_r = L/2V_r$, t_s
 $\sim 1.5 t_r$

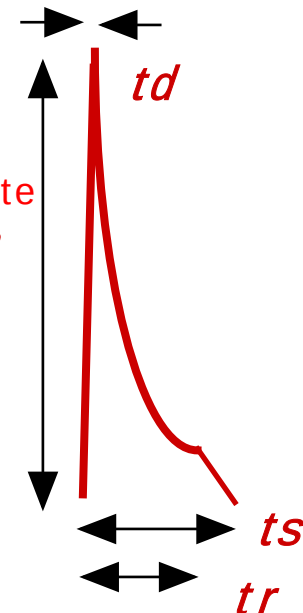
$$V_m \approx \frac{\Delta\sigma \sqrt{2LV_R f_c}}{\mu}$$

$\Delta\sigma = 5 \text{ MPa} \sim 20 \text{ MPa}$

$f_c \sim f_{\text{max}}$

Lowpassfiltered peak slip rate V_m
 f_c : cutoff frequency
 Day(1982)

$t_d \sim 0.2$

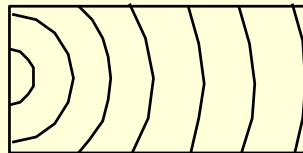


Application of the approximate expression of slip rate time function to strike slip fault

CASES

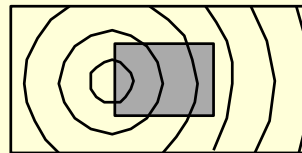
Shallow Strike Slip Fault

CASE-A

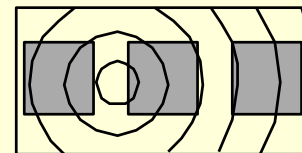


CASE-B

CASE-B1



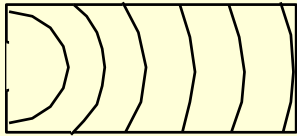
CASE-B3



CASE-C



CASE-A



CASE - A

Fault normal ground velocity

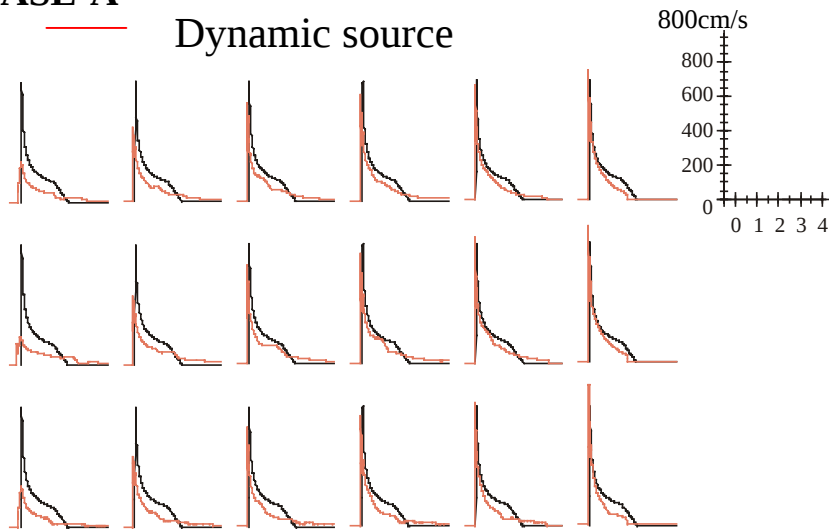
Fault



CASE-A

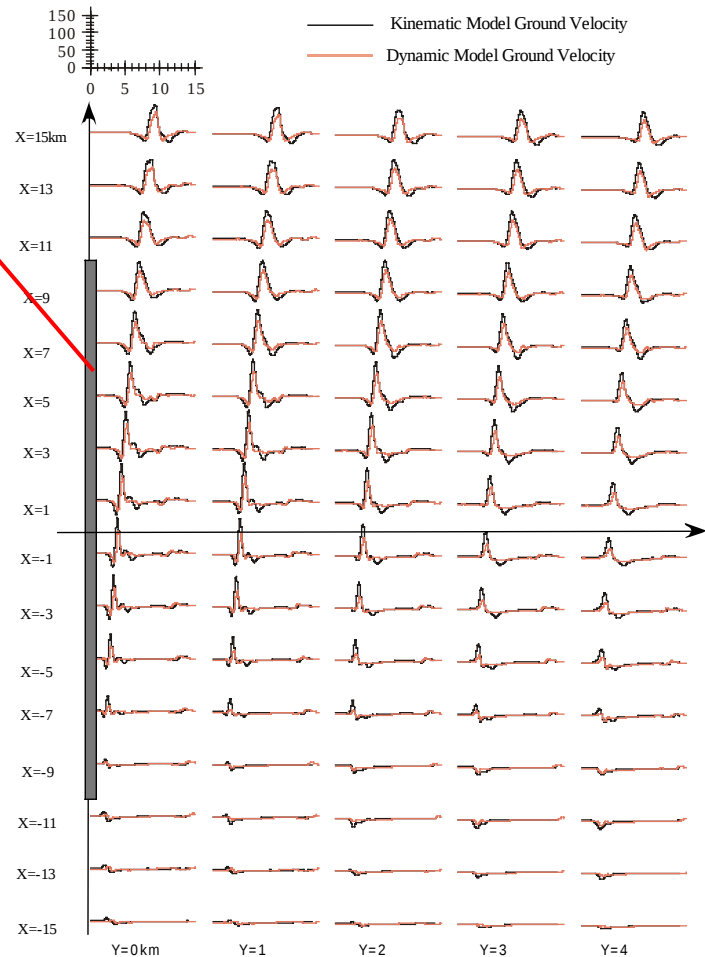
Approximate expression

Dynamic source



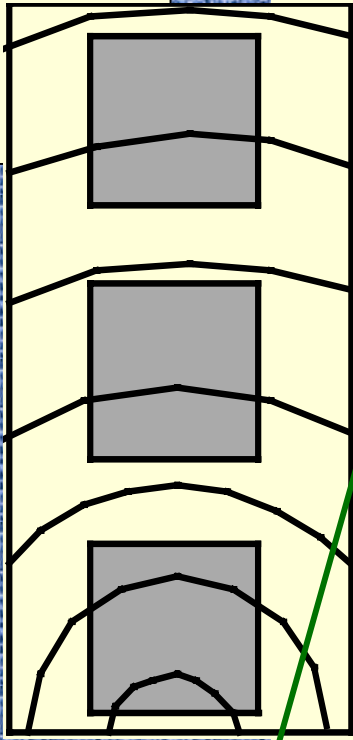
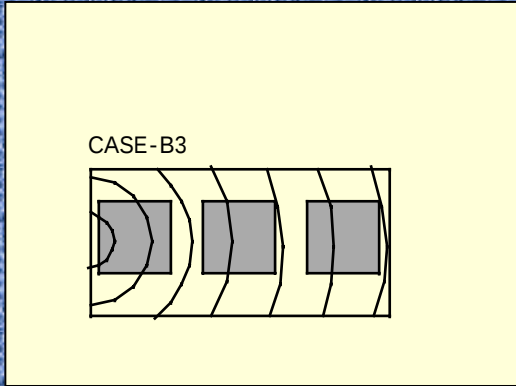
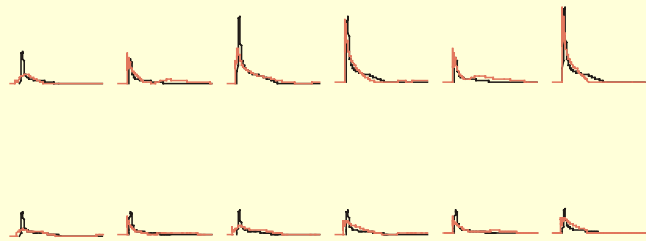
CASE-A

Ground Velocity
Fault Normal Component



CASE-B3

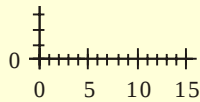
CASE-B3'



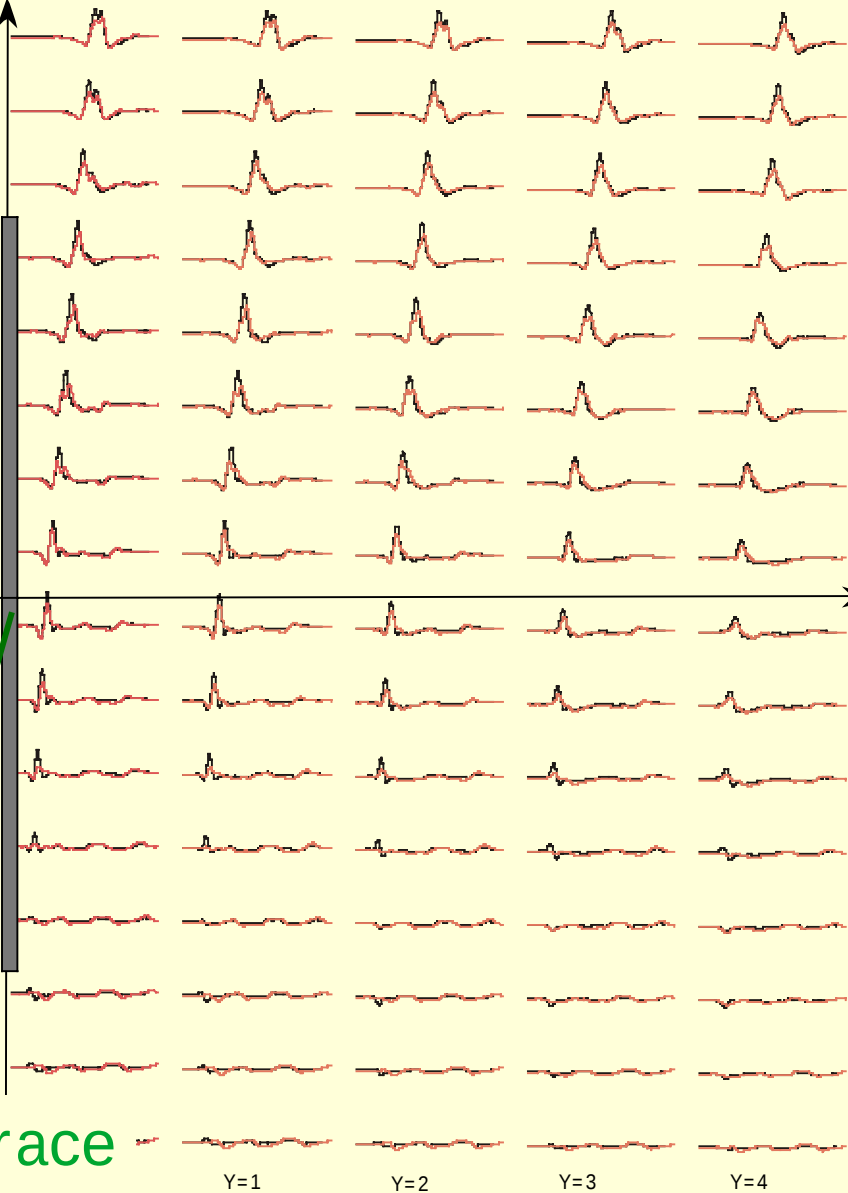
X=15km
X=13
X=11

X=-11
X=-13

CASE-B3 Fault Normal



Kinematic Model Ground Velocity
Dynamic Model Ground Velocity



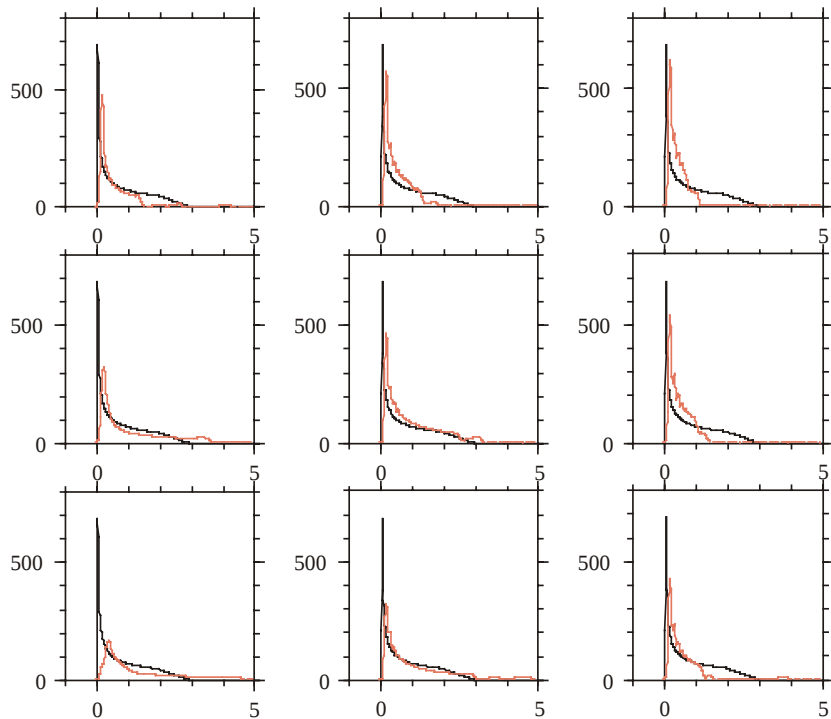
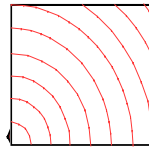
Fault Trace

CASE-C

Slip Rate Time Functions

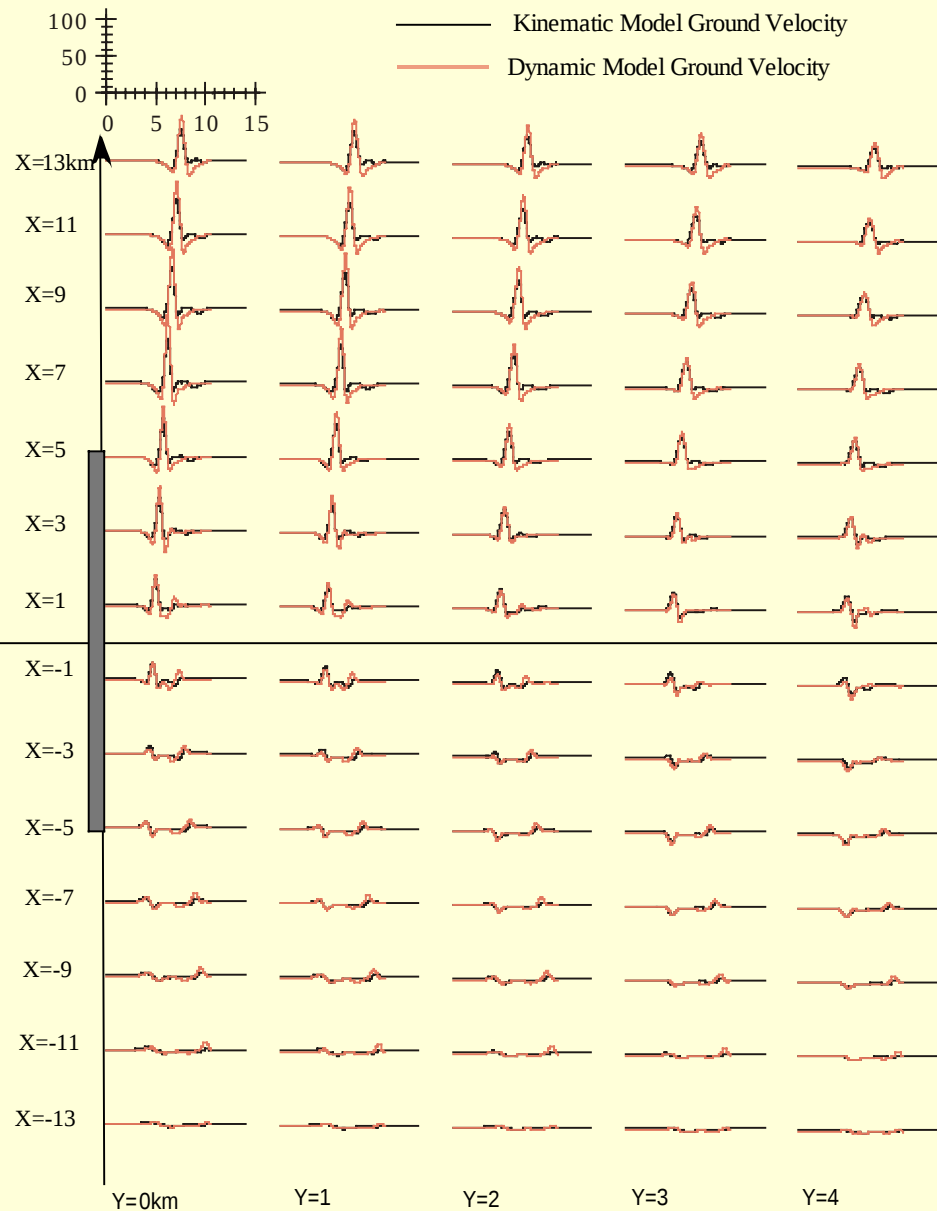
CASE-C0

Starting Point

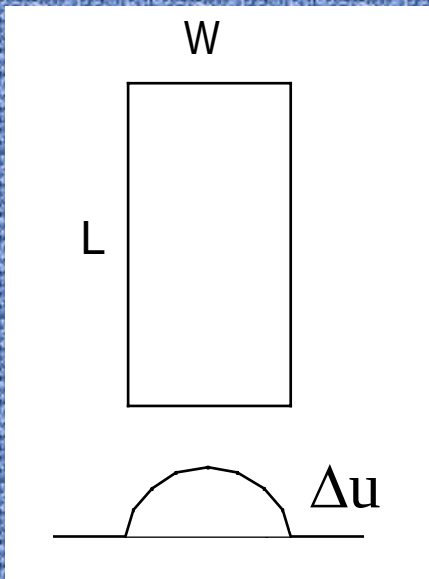


CASE-C0

Ground Velocity
Fault Normal Component



Slip distribution



Approximate expression of slip

$$\Delta u(x,y) \approx \frac{\Delta \sigma}{\mu} \frac{\sqrt{1 + \left(\frac{L}{W}\right)^2}}{1 + \frac{4}{3} \left(\frac{L}{W}\right)^2} W \sqrt{1 - \left(\frac{2y}{W}\right)^2} \sqrt{(2-\eta)\eta}$$

$$\eta(x) = \begin{cases} |L - 2x| / W & \text{if } |L - 2x| < W \\ 1 & \text{if } |L - 2x| \geq W \end{cases}$$

Chiner ry(1960) and Day(1982)

Computer simulation of strong ground motion using dynamic faulting process

Peak Velocity

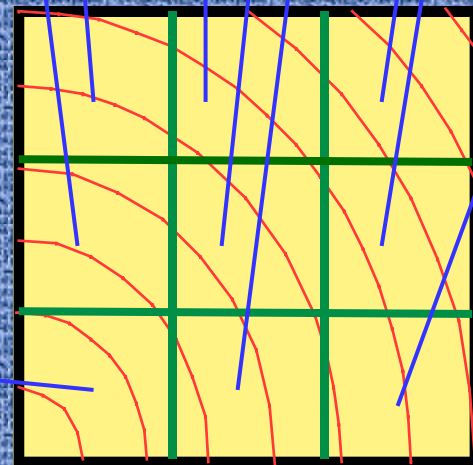
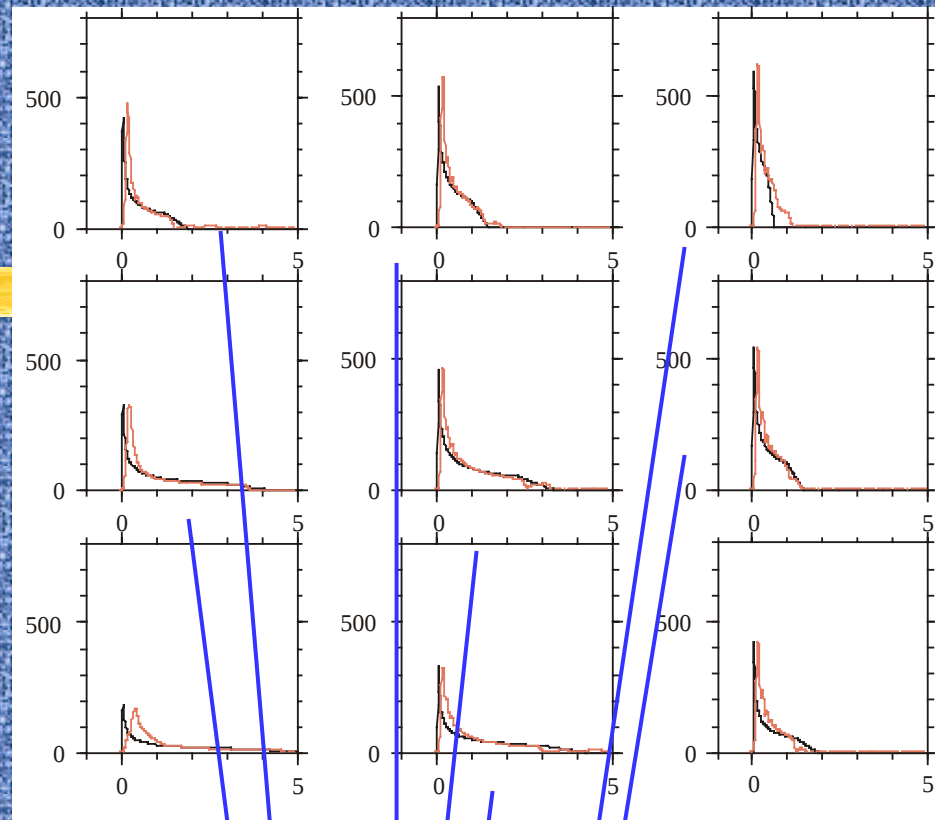
$$V_{\max} = C(v) \frac{\Delta\sigma}{\mu} \beta \sqrt{\frac{2rf_{\text{cut}}}{v} + 1}$$

Rise time

$$Tr(x,y) = \frac{w}{2v} \left[1 - \left(\frac{2y}{w} \right)^2 \right] \left[2 - \xi(x) \right] \xi(x)$$

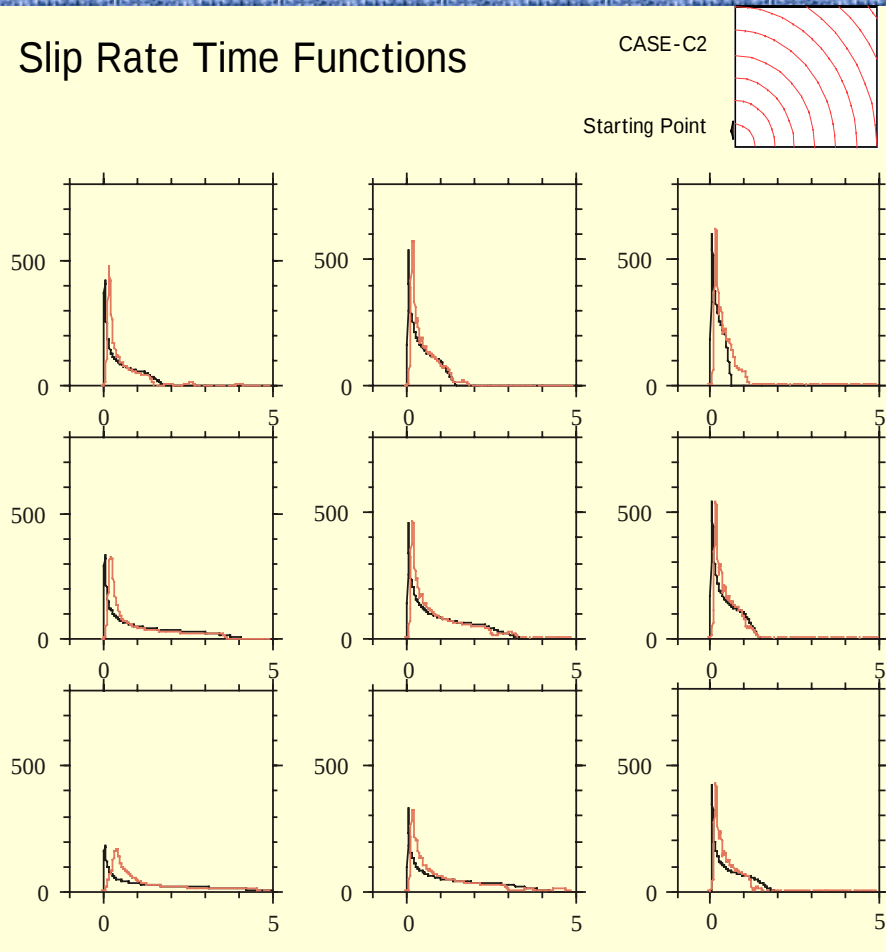
$$\xi(x) = \begin{cases} 2 \frac{|L-x|}{w} & \text{if } |L-x| < w/2 \\ 1 & \text{if } |L-x| \geq w/2 \end{cases}$$

Day(1982)



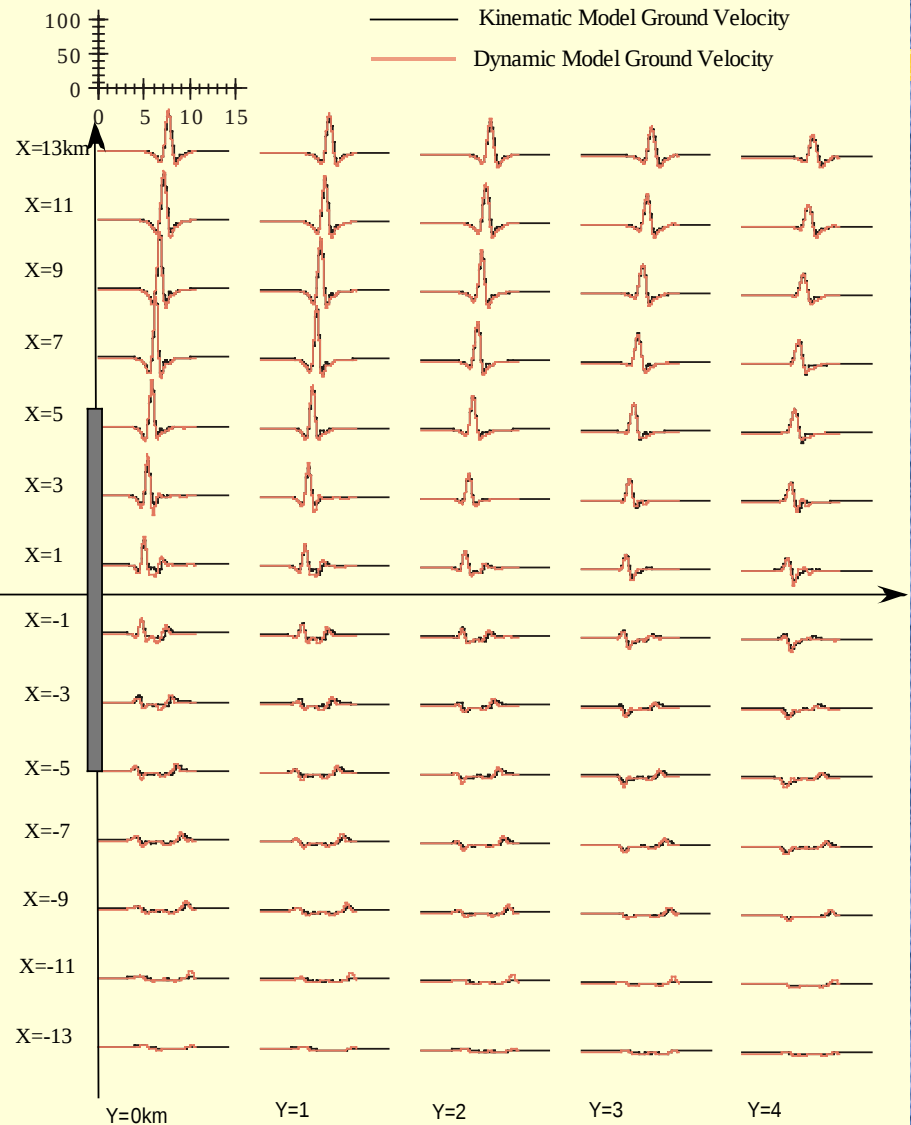
CASE-C'

Slip Rate Time Functions



CASE-C2

Ground Velocity Fault Normal Component



結論

- 動力学モデルの数値シミュレーションに基づく滑り速度時間関数の作成
- 滑り速度時間関数の近似式による断層近傍の地震波形
- 動的モデルによる地震波形と一致

今後

- 具体例を通して精密化
- (もっともっと不均質な場合への適用)
- 短周期
 - Slip rate time functionよりも破壊過程が効く

応力降下量分布

