

## A Prototype Scintillating-Fibre Tracker for the Cosmic-ray Muon Tomography of Legacy Nuclear Waste Containers

**M. Murray**, A. Clarkson, D. J. Hamilton, G. D. Hill, M. Hoek, D. G. Ireland, R. Kaiser, T. Keri, S. Lumsden, David F. Mahon, B. McKinnon, S. Nutbeam-Tuffs and G. Yang Nuclear Physics Group, University of Glasgow, Kelvin Building, University Avenue, Glasgow, G12 8QQ, Scotland, UK

J. R. Johnstone, P. Knight, C. Shearer, C. Staines and C. Zimmerman UK National Nuclear Laboratory, Central Laboratory, Sellafield, Seascale, Cumbria, CA20 1PG, England, UK

Muon and Neutrino Radiography 2013 (MNR2013) Detector and Electronics Workshop Friday 26th July 2013

Friday, 26 July 2013



# **Presentation Overview**

- UK legacy nuclear waste and the Glasgow MT project
- Glasgow MT detector
  - Design characteristics
  - Construction
  - Performance studies
  - Simulation studies
- Image reconstruction
- Preliminary results and simulation verification
- Summary



# **Presentation Overview**

- UK legacy nuclear waste and the Glasgow MT project
- Glasgow MT detector
  - Design characteristics
  - Construction
  - Performance studies
  - Simulation studies
- Image reconstruction
- Preliminary results and simulation verification
- Summary







# **Presentation Overview**

- UK legacy nuclear waste and the Glasgow MT project
- Glasgow MT detector
  - Design characteristics
  - Construction
  - Performance studies
  - Simulation studies
- Image reconstruction
- Preliminary results and simulation verification
- Summary







# **UK Legacy Nuclear Waste**

- Currently, there are 8 nuclear power plant facilities operational in the UK
  - 1 Magnox reactor, 6 advanced gas-cooled reactor sites and 1 pressurised-water reactor
  - Government policy is to undertake reactor new-build at several sites within the UK
- A consequence nuclear power is the generation of low-, intermediateand high-level waste products
  - Legacy silos and waste ponds
  - ILW waste containers (see below)



- The UK's nuclear waste reprocessing is currently performed at Sellafield, Cumbria in the north-west of England
- On Sellafield's site significant volumes of ILW and HLW are stored in highly-engineered structures
- In order to characterise this current (and legacy) waste, techniques to clearly understand waste performance and storage parameters are essential
- Development of characterisation techniques (such as MT) assist in mitigating the risks inherent with long-term storage of these materials





# The Glasgow Muon Tomography Project

Industrial collaboration with UK National Nuclear Laboratory (NNL) undertaken on behalf of Sellafield Ltd. (and the UK Nuclear Decommissioning Authority)







Began as a feasibility study:

Could a scintillating-fibre MT system be used in the non-destructive assay of legacy nuclear waste containers at Sellafield?

- Small-scale prototype designed and constructed in Glasgow after initial simulation studies confirmed the potential of the technology
- First imaging results on a test setup of objects are presented here





# The Glasgow Muon Tomography Project

 Industrial collaboration with UK National Nuclear Laboratory (NNL) undertaken on behalf of Sellafield Ltd. (and the UK Nuclear Decommissioning Authority)



• Began as a feasibility study:

Could a scintillating-fibre MT system be used in the non-destructive assay of legacy nuclear waste containers at Sellafield?

- Small-scale prototype designed and constructed in Glasgow after initial simulation studies confirmed the potential of the technology
- First imaging results on a test setup of objects are presented here









### The Glasgow MT Detector: Muon Event Generator and GEANT4 Simulation Studies



- Cosmic-ray muons are generated by a standalone code based on well established and accurately measured properties:
  - Mean momentum, p<sub>mean</sub> of 3.35 GeV/c with p<sup>-2.7</sup> slope at high momenta
  - The angular distribution has a characteristic  $\cos^2 \theta$  dependence
  - Muon flux of approximately 1cm<sup>-2</sup> min<sup>-1</sup>
    - active area cut out

top-down view of the module shows the

- GEANT4, developed at CERN, is the '*industry standard*' detector simulation framework in particle and nuclear physics
- 'Active' components of the module 'sandwich' structure and materials accurately modelled in GEANT4

with 'V'-shaped grooves in X-plane (top-side) and Y-plane (under-side)

Friday, 26 July 2013

٠

- Expected material discrimination obtained from GEANT4 simulations studies performed in an air Ē ~ matrix:
- 10x10x10cm<sup>3</sup> blocks of material with 1 day muon exposure

Test case for prototype MT system

Clear separation of low-, medium- and high-Z materials using scattering parameters -



in Glasgow





- Experimental test setup in Glasgow simulated (shown opposite without top module)
- Data taking commenced 2012 to verify the initial, ٠ promising simulation results

### The Glasgow Detector: More GEANT4 Simulation Studies





- Prototype detector setup consists of four tracking modules
  - 2 orthogonal layers of 128 scintillating fibres
  - 'Sandwich' structure with flat and machine-grooved Rohacell<sup>®</sup> (polymethyacrylimide) support sheets and Aluminium baseplate

- Layers bonded with optical glue
- Tedlar<sup>®</sup> and nylon tubing ensure light-tightness





- Fibres held in place by custom-made distribution blocks at edges of Aluminium baseplate and PMT
- All four modules held in place in an Aluminium-profile stand with alignment pins in each module



- Prototype detector setup consists of four tracking modules
  - 2 orthogonal layers of 128 scintillating fibres
  - 'Sandwich' structure with flat and machine-grooved Rohacell<sup>®</sup> (polymethyacrylimide) support sheets and Aluminium baseplate

- Layers bonded with optical glue
- Tedlar<sup>®</sup> and nylon tubing ensure light-tightness





- Fibres held in place by custom-made distribution blocks at edges of Aluminium baseplate and PMT
- All four modules held in place in an Aluminium-profile stand with alignment pins in each module



- Prototype detector setup consists of four tracking modules
  - 2 orthogonal layers of 128 scintillating fibres
  - 'Sandwich' structure with flat and machine-grooved Rohacell<sup>®</sup> (polymethyacrylimide) support sheets and Aluminium baseplate

- Layers bonded with optical glue
- Tedlar<sup>®</sup> and nylon tubing ensure light-tightness





- Fibres held in place by custom-made distribution blocks at edges of Aluminium baseplate and PMT
- All four modules held in place in an Aluminium-profile stand with alignment pins in each module



- Prototype detector setup consists of four tracking modules
  - 2 orthogonal layers of 128 scintillating fibres
  - 'Sandwich' structure with flat and machine-grooved Rohacell<sup>®</sup> (polymethyacrylimide) support sheets and Aluminium baseplate

- Layers bonded with optical glue
- Tedlar<sup>®</sup> and nylon tubing ensure light-tightness





- Fibres held in place by custom-made distribution blocks at edges of Aluminium baseplate and PMT
- All four modules held in place in an Aluminium-profile stand with alignment pins in each module



### **Detector Components:** Scintillating Fibres and Hamamatsu H8500 MAPMTs



- SAINT-GOBAIN scintillating fibres used
  - 2mm pitch with active core of 97% width
  - Polystyrene-based core with PMMA (polymethylmethacrylate) optical cladding (3% width)
- Polished fibre (shown opposite)
- Aluminium collars glued on to ensure uniform contact with PMT
- Chosen for their robustness and scaleability



PMT relative-gain maps

- HAMAMATSU H8500 MAPMT (8x8 array segmented anode)
- 2 fibres multiplexed to one pixel via a dedicated coupling scheme to ensure successful fibre identification
- PMTs gain-tested at operational voltages
- Custom-built PCB boards used to read-out to 32-channel OCAEN QDC units





### **Detector Components:** Scintillating Fibres and Hamamatsu H8500 MAPMTs



- SAINT-GOBAIN scintillating fibres used
  - 2mm pitch with active core of 97% width
  - Polystyrene-based core with PMMA (polymethylmethacrylate) optical cladding (3% width)
- Polished fibre (shown opposite)
- · Aluminium collars glued on to ensure uniform contact with PMT
- Chosen for their robustness and scaleability



PMT relative-gain maps

- **HAMAMATSU** H8500 MAPMT (8x8 array segmented anode)
- 2 fibres multiplexed to one pixel via a dedicated coupling scheme to ensure successful fibre identification
- PMTs gain-tested at operational voltages
- Custom-built PCB boards used to read-out to 32-channel OC CAEN QDC units





### The Glasgow Detector: Data-taking and Performance Studies

- Multi-fold trigger on Dynode-12 signals from the detector PMTs
- Highest gain-corrected QDC signal above pedestal chosen as 'hit'
- Only events with a hit in each layer are analysed
- Narrow pedestals across the 512 QDC channels
- PMT characterisation and cross-talk investigations completed.
- Relative gain-maps obtained via laser scan
- Multiplicities (~1.5 clusters per 1<sup>8</sup> event across all PMTs)
- Detector performance stable over long time periods
- Alignment optimisation undertaken to compensate for minor structural misalignments (less than 5mm)





. Schultz et al., "Statistical Reconstruction for Cosmic Ray Muon Tomography" - IEEE Transactions on Image Processing 16 (2007

- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where  $\Delta x$  and  $\Delta \theta_x$  are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and  $\lambda_j$  (n) is the  $\lambda$  value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$





- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> (n) is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$



### Image Reconstruction: Maximum Likelihood Expectation Maximisation (ML-EM)

### track from top modules



- Imaging volume is split into small volume elements called ٠ voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is ٠ assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *i*th voxel is ٠ expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where  $\Delta x$  and  $\Delta \theta_x$  are the spatial and angular deviations of the track (in the x direction) due to scattering,  $L_{ii}$  is the pathlength in the voxel,  $T_{ii}$  is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and  $\lambda_i$ (n) is the  $\lambda$  value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as: •

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$



# Image Reconstruction:

## Maximum Likelihood Expectation Maximisation (ML-EM)

L. Schultz et al., "Statistical Reconstruction for Cosmic Ray Muon Tomography" - IEEE Transactions on Image Processing 16 (2007

### track from top modules



- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$





- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$





- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$



- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$





- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$



- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$





- Image Reconstruction: Maximum Likelihood Expectation Maximisation (ML-EM)
  - L. Schultz et al., "Statistical Reconstruction for Cosmic Ray Muon Tomography" IEEE Transactions on Image Processing 16 (2007)
- Imaging volume is split into small volume elements called voxels
- Prior knowledge of the Point of Closest Approach (PoCA) is needed
- This method provides information on every voxel the muon is assumed to have passed through.
- The scattering likelihood of the *i*th muon in the *j*th voxel is expressed as:

$$S_{ij}^{(n)} = f(\Delta x, \, \Delta \theta_x, \, L_{ij}, \, T_{ij}, \, \lambda_j^{(n)})$$

- where Δx and Δθ<sub>x</sub> are the spatial and angular deviations of the track (in the x direction) due to scattering, L<sub>ij</sub> is the pathlength in the voxel, T<sub>ij</sub> is the 3-D pathlength from the voxel exit point to the exit point from the imaging volume (shown opposite) and λ<sub>j</sub> <sup>(n)</sup> is the λ value of the current iteration.
- The  $\lambda$  value of the next iteration is determined as:

$$\lambda_j^{(n+1)} = \frac{1}{M_j} \sum_i S_{ij}^{(n)}$$



# **Preliminary Results**



Friday, 26 July 2013



# **Preliminary Results**



- Excellent agreement between the experimental data taken on the prototype detector and the simulated data
- Clear separation observed between the air, steel bar and the two high-Z materials



- Muon tomography is increasingly being used in the nondestructive assay of large and/or shielded objects with applications in fields ranging from archaeology to national security
- In collaboration with the UK National Nuclear Laboratory, the Nuclear Physics group at the University of Glasgow has developed and constructed a prototype MT system using scintillating fibres
- First results from this small-scale prototype in Glasgow verify initial simulation and feasibility studies by discriminating between low-, medium- and high-Z materials
- Work underway on the development of a full-scale detector system with a view to imaging legacy waste containers





x coordinate

# Summary



# Acknowledgements

I would like to thank the organising committee for giving me the opportunity to present the results and work undertaken by the Nuclear Physics group at the University of Glasgow in collaboration with the UK National Nuclear Laboratory.

In addition, on behalf of the project, I would like to acknowledge the funding contribution from the NDA and Sellafield Ltd. which enabled this research to be undertaken.

