Muography applied to nuclear waste storage sites **Raffaello D'Alessandro** (Università di Firenze and INFN-Firenze) on behalf of the MURAVES collaboration International Workshop Muographers 2014, Tokyo For the material in these slides I would like to thank: David Mahon from Glasgow University and especially Nicola Mori from the University of Florence

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Nuclear waste management, i.e. Sellafield



Images courtesy of Sellafield Ltd. (www.sellafieldsites.com)





The swarf is stripped from the fuel element in the Fuel Handling Plant. The fuel is then transported to the Magnox Reprocessing Plant.

Magnox Fuel Elements

Uranium fuel surrounded by a magnesium alloy 'swarf' cladding. Before reprocessing, irradiated Magnox fuel must be stored for at least 180 days in ponds to allow short lived fission products to decay.

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Long-term Storage of ILW The ILW is stored in 500-litre stainless-steel waste containers (shown here for a test drum with outer section removed) or in 3m³ boxes.





Magnox Swarf Storage Silos

Prior to the encapsulation of dry waste, 'wet storage' of Magnox swarf was undertaken within silo facilities. Retrieval and treatment operations are in development.

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Encapsulated Swarf

The swarf stripped from the

fuel elements is Intermediate

Level Waste (ILW). Shown is

a cross section view of ILW

which has been grouted in

cement for long term storage.

Scenarios

Scenario #1:



With ideal detector placement (i.e. above and below) can a 10cm cube of uranium in Scenario #1 be imaged by absorption muography ? This is usually the realm of multiple scattering measurements. And what about smaller cubes ?

Scenario #2:

In principle, it is possible to obtain an image from this silo though the size, timescales and image resolution are yet to be fully established. This is the Scenario for which I will show some preliminary feasibility studies.

Scenario #3

If Scenario 2 \rightarrow OK, then imaging of a full scale silo will be investigated. Determine which of the compartments (if any) can be imaged successfully using the Muography approach.

The Muray detector

• TRIANGULAR SCINTILLATOR BARS WITH WLS FIBERS

SILICON PHOTOMULTIPLIERS

CUSTOM FRONT END ELECTRONIC BASED ON
EASIROC ASIC

- * LOW POWER CONSUMPTION
- * SELF TRIGGERING
- * TIME MEASUREMENT
- * CHARGE MEASUREMENT
- LOW COST
- CUSTOM STANDALONE DAQ

DETECTOR PERFORMANCES:

SPATIAL RESOLUTION: some mm TIME RESOLUTION : < 1ns PLANE EFFICIENCY : > 95% TOTAL POWER CONSUM.: < 50 W COST: O(100) k€ / 1 m² detector



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Particular of SiPMs bonded on the PCB carrier

module: 32

bars with WLS fibers

One

The full detector: 3 X-Y planes , 384 ch



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Simulations with Geant4

- 2 XY layers made of plastic scintillating bars
- Triangular bar section
- 2m x 2m detector surface
- Can be placed in any position and orientation
- Can be deployed multiple times inside simulation scenario (eventually)



Geant 4 simulation, Scenario 2





- Background simulation without U
- Realistic input spectrum: Tanaka et al., Hyperf. Int. 138 (2001) 521-526





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Muon absorption map

- 5×10^{10} generated events $\rightarrow \sim 80$ days
- $\sim 2 \times 10^8$ events inside acceptance
- Difference map @ X=0 (i.e. YZ layer containing the U sample)



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Complicate the picture

- Sellafield scenario #2:
 - Cylindrical storage silo,
 - Concrete + reinforced concrete
- Uranium debris:
 - Unknown number/position,
 - Expected size ~ some cm
- Unknown "noise" content:
 - Variable concrete density,
 - High/low density debris,
 - Clothes, bricks, steel rods,
 - Air bubbles

Parameters

- Detector size ~ distance from target
- Target (U) size << detector size

 Need to estimate the expected event count when no U is present ("background")



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Checklist

- Simulation code:
 - General simulation code developed in Florence, based on Geant4
- Realistic muon generator:
 - Shape, normalization
- Scenario #2 geometry implementation:
 - Realistic detector implementation
 - Reconstruction and analysis routines
- # of simulated events \rightarrow acquisition time

- Based on ground measurements with a magnetic spectrometer:
 - 0.1 GeV/c
 - $0 \deg < \theta < 80 \deg$
- Smoothing + discretization
- Hit&Miss sampling of (Ek, θ)
- Random generation point on a horizontal surface

Bonechi, L., et al., Intl. Cosmic Ray Conf. Proc. (2005), 283

Muon Generator



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• Homogeneous materials

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- Densities (g/cm3): reinforced concrete 5, stainless steel 8.03, concrete 2.3, uranium 18.95
- Arbitrary number of U and air cubes with arbitrary position and size



Simulation (continued)

- Full detector simulation (triangular bars, etc.) time consuming.
- Approximated to a $2x2m^2$ plane with 3mm impact point resolution.
- Flux parameters:
 - Ek € [0.7, 130] GeV
 - $\theta \in [0, 80] \text{ deg}, \phi \in [-90, 90] \text{ deg}$
- Generation surface:
 - $z = 5 m, x \in [-3, 65] m, y \in [-10, 10] m$
 - Area: 1360 m², Full coverage of the detector-silo acceptance
- Acceptance check:
 - $\sim 10^{12}$ generated, 1.2 x 10⁹ simulated
- Computation:
 - CPU time: \sim (1.5 days * 300 cores)
 - Size of output: ~ 330 GB

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- (10 cm)3 U:
 - (0, 0.2, 1.5) m (center)
 (0.5, -0.2, 1) m (bottom-far)
- (5 cm)3 U:
 - (0, -0.15, 2) m (center)
 - (-1, -0.15, 3.5) m (top-near)
- (2 cm)3 U:
 - (0, 1, 2.6) m (lateral)
 - (0, -0.2, 2.3) m (center)
 - (-0.8, -0.8, 2.5) (lateral-near)
- (10 cm)3 air:
 - (0, -0.2, 1.3) m (center-bottom)

U and air samples



S/N estimation

• Results are obtained by subtracting two maps :

- one with a "signal" and the other "background only" from a reference silo
- In difference maps, signal is computed as the difference between two independent Poisson variables → Skellam distribution

•
$$\sigma^2 = \mu 1 + \mu 2$$

- $S/N = (N1 N2)/sqrt(\mu 1 + \mu 2)$
- $S/N \approx (N1 N2)/sqrt(N1 + N2)$

Some Preliminary Results



Difference map - X=-100.000000



• The 5 cm U cube is clearly visible with S/N = 6

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S/N map - X=-100.000000

Z [cm]

Other sizes





• The 10 cm U cube is clearly visible with S/N = 6

• Smaller cubes and the air gap are not visible

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-2

-4

-6

-8

S/N vs Acquisition Time



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Conclusions and acknowledgments

- The simulation that has been shortly described in these slides has been set up thanks to the collaboration between two Italian groups (belonging to INFN and Physics Departments of Naples and Firenze), NNL and the group from Glasgow headed by Dr. Craig Shearer and Dr. David Mahon.
- Details of the silos geometries were collected by Dr. Mahon (Glasgow) and discussed with the Italian teams during several meetings.
- In this framework Nicola Mori has implemented a simulation framework based on Geant4
- Lorenzo Bonechi provided precious data on which we calibrated our muon generator.
- A paper has been submitted to Applied Physics Letters, http://arxiv.org/abs/1411.2382 MNR 2014, Tokyo 12 November 2014

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